

Resource Summary Report

Generated by [FDI Lab - SciCrunch.org](https://fdi-lab.sci-crunch.org) on Apr 19, 2025

Simbody(tm): SimTK Multibody Dynamics Toolset

RRID:SCR_002684

Type: Tool

Proper Citation

Simbody(tm): SimTK Multibody Dynamics Toolset (RRID:SCR_002684)

Resource Information

URL: <https://simtk.org/home/simbody>

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Description: This project is a SimTK Core toolset providing general multibody dynamics capability, i.e., the capability to solve Newton's 2nd law $F=ma$ in any set of coordinates. The techniques of rigid body mechanics are used to provide results in Order(n) time for any set of n coordinates. This can be used for internal coordinate modeling of molecules, or for coarse-grained models based on larger chunks. It is also useful for large-scale mechanical models, such as neuromuscular models of human gait. Simbody is provided as an open source, object-oriented C++ API and delivers high-performance, accuracy-controlled science/engineering-quality results. Binaries of this software are bundled with other SimTK Core modules.

Synonyms: Simbody

Resource Type: simulation software, software application, software resource

Defining Citation: [PMID:25866705](https://pubmed.ncbi.nlm.nih.gov/25866705/)

Keywords: articulated body, coarse-grained molecule modeling, constrained motion, internal coordinates, mechanical simulation, mechanics, molecular dynamics, multibody dynamics, rigid body, simtk core, skeletal mechanics, torsion coordinates

Funding:

Availability: Public, Free, Acknowledgement requested

Resource Name: Simbody(tm): SimTK Multibody Dynamics Toolset

Resource ID: SCR_002684

Alternate IDs: nif-0000-23309

Record Creation Time: 20220129T080214+0000

Record Last Update: 20250419T054857+0000

Ratings and Alerts

No rating or validation information has been found for Simbody(tm): SimTK Multibody Dynamics Toolset.

No alerts have been found for Simbody(tm): SimTK Multibody Dynamics Toolset.

Data and Source Information

Source: [SciCrunch Registry](#)

Usage and Citation Metrics

We have not found any literature mentions for this resource.